



## Research papers

# On the estimation of spatially representative plot scale saturated hydraulic conductivity in an agricultural setting



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## ABSTRACT

Spatially representative estimates of saturated hydraulic conductivity,  $K_s$ , are needed for simulating catchment scale surface runoff and infiltration. Classical methods for measuring  $K_s$  are time-consuming so sampling campaigns need to be designed economically. Important insights can be obtained by experiments directed to understand the controls of  $K_s$  in an agricultural setting and identify the minimum number of samples required for estimating representative plot scale  $K_s$ . In this study, a total of 131 double-ring infiltrometer measurements were made on 12 plots in a small Austrian catchment. A statistical analysis of  $K_s$  across the catchment suggests  $K_s$  to be only slightly influenced by physical and topographical soil characteristics while land use is the main control. The highest values of  $K_s$  were observed in arable fields, with a median of about 3 times and a coefficient of variation (CV) of about 75% of those in grassland areas. An uncertainty analysis aimed at determining the minimum number of  $K_s$  measurements necessary for estimating the geometric mean of  $K_s$  over a given area with a specified accuracy suggests that, beyond a specific and plot-size dependent number of measurements, the benefit of any extra measurement is small. The confidence interval of the geometric mean of  $K_s$  decreases with the number of measurements and increases with the size of the plot sampled. Applications of these findings for designing field campaigns are discussed.

## 1. Introduction

The hydraulic conductivity of saturated soils,  $K_s$ , is a key parameter controlling various hydrological processes, including rainfall partitioning into infiltration and surface runoff. Accurate estimates of  $K_s$  are needed for modeling local infiltration into homogeneous (Parlange et al., 1982) and layered soils (Govindaraju et al., 2012), as well as for upscaling infiltration models (Smith and Goodrich, 2000; Corradini et al., 2011). Saturated hydraulic conductivity is highly variable in space due to soil structure (Dexter et al., 2004), texture (Saxton et al., 1986; Jabro, 1992), landscape position (Mohanty et al., 1994), and land cover and management practices (Alletto and Coquet, 2009; Bonell et al., 2010), it also depends on scale (Sobieraj et al., 2004; Lai and Ren, 2007). Saturated hydraulic conductivity typically varies even more than two orders of magnitude in space. Baiamonte et al. (2017) performed 150 infiltration measurements in a Sicilian basin and observed values of  $K_s$  that ranged from less than  $1 \text{ mm h}^{-1}$  to more than

$8000 \text{ mm h}^{-1}$ . Papanicolaou et al. (2015) conducted about 120 infiltration experiments on three hillslopes with different agricultural management practices in Iowa and observed  $K_s$  values that ranged from  $0.15 \text{ mm h}^{-1}$  to  $360 \text{ mm h}^{-1}$ . Similarly, Loague and Gander (1990) carried out 157 infiltration measurements in a small rangeland catchment of area  $0.1 \text{ km}^2$  (R-5, Oklahoma) and obtained values of  $K_s$  approximately variable by two orders of magnitude in space. Furthermore, Sharma et al. (1987) performed infiltration experiments in two lateritic Australian catchments ( $0.94 \text{ km}^2$  and  $0.81 \text{ km}^2$ ) and found  $K_s$  values in the range  $8.33\text{--}946 \text{ mm h}^{-1}$  and  $237\text{--}1646 \text{ mm h}^{-1}$ , respectively.

Woolhiser et al. (1996) found that runoff hydrographs were strongly affected by variations in saturated hydraulic conductivity at the hillslope scale, especially for small runoff events. Taskinen et al. (2008) investigated the effects of spatial variability of  $K_s$  on overland flow in a small agricultural catchment by analyzing 2000 synthetic rainfall-runoff events generated from observed rainfall events with runoff

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modelled using different spatially variable  $K_s$  fields. They found the greatest differences in the first flow peak and in the rising part of the hydrograph. Hu et al. (2015) analyzed the effects of  $K_s$  variability on runoff simulations in a small watershed on the Chinese Loess Plateau and found that total and peak discharges were underestimated if the spatial variability of  $K_s$  was completely ignored or only partially considered. Assouline and Mualem (2002) examined the effects of the spatial variability of soil hydraulic properties combined with the formation of a sealing layer at the soil surface. They deduced that the hydrological response of arid and semiarid catchments is dominated by these effects. Assouline and Mualem (2006) showed that infiltration into crusted soils experiences substantial changes for the presence of  $K_s$  spatial heterogeneity, particularly for loam soils. Accounting for  $K_s$  spatial variability is therefore essential.

In addition to undisturbed soil core sampling, several experimental techniques are available for estimating  $K_s$  through in-situ infiltration measurements. The most commonly used devices are: tension permeameters, e.g. the CSIRO disc permeameter (Perroux and White, 1988), single ring infiltrometers (Lassabatère et al., 2006; Bagarello et al., 2004, 2014a; Ahmed et al., 2014), double-ring infiltrometers (Swartzendruber and Olson, 1961), constant-head well permeameters, e.g. the Guelph permeameter (Reynolds and Erlick, 1985), and rainfall simulators, e.g. the Guelph rainfall simulator (Tossell et al., 1987). The device choice conditions the estimated values of  $K_s$  (Verbist et al., 2013; Bagarello et al., 2014a) due to different factors (Reynolds et al., 2000) such as size of investigated soil, sample collection procedure, flow geometry, and estimate of other soil parameters (e.g., soil sorptivity, saturated water content) necessary to derive the value of  $K_s$  applying specific data analysis procedures.

Widely used techniques to determine  $K_s$ , such as the traditional well permeameter and ring infiltrometer, rely on the attainment of a steady-state flow rate, so that the time required to carry out each measurement is usually high. Other techniques do not require to achieve steady conditions (Bagarello et al., 2004, 2014b) but, in any case, their use at the catchment scale represents a challenge. Speeding up the measurement operations with the purpose of achieving detailed  $K_s$  maps over large areas is therefore one of the greatest issues to be addressed in spatial infiltration studies. Pedotransfer functions which estimate  $K_s$  from more easily measurable soil physical properties (Bouma, 1989) and statistical approaches to extrapolate  $K_s$  from a small number of measurements to the entire catchment are some of the approaches adopted to reduce the time demand of extensive field measurement campaigns.

However, macropores and other preferential flow paths often dominate the infiltration behavior even more than the characteristics of the soil matrix (as quantified by porosity, texture etc.), so it is usually advantageous not to rely only on pedotransfer functions from the literature but to perform at least a few  $K_s$  measurements in the catchment of interest (Bouma et al., 2011). Regarding the number of measurements required, Vieira et al. (1981) studied the spatial variability of 1280 field-measured infiltration rates using geostatistical concepts. They argued that 128 samples were sufficient to obtain nearly the same information as obtained from 1280 samples. Ahmed et al. (2015) conducted an uncertainty analysis on 722 infiltration measurements in six roadside drainage ditches (grassy swales, i.e. shallow, open vegetated roadside drainage channels designed to convey stormwater runoff to storm sewers or water receiving bodies) and concluded that approximately twenty infiltration measurements were the minimum number to obtain a representative geometric mean of  $K_s$  of a swale that was less than 350 m long, with an acceptable level of uncertainty. The identified minimum number was related to the width of the 95% confidence interval that in logscale was about equal to 2.

Skøien and Blöschl (2006) found that the required number of samples depends on the spatial correlation of  $K_s$  as well as on the measurement setup. They investigated the effect of spacing (average distance between samples), extent (size of the domain sampled) and

support (averaging area of one sample), i.e. the “scale triplet” as termed by Blöschl and Sivapalan (1995), on the estimates of mean, spatial variance and complete range of a variable in a landscape. For each of the chosen combinations of spacing, support and extent they generated 1000 synthetic random fields and sampled from them according to the selected scale triplet. In what they termed “single realization case”, they compared the sample mean and sample variance with the mean and variance of the entire random field of the same realization. They found that the estimation uncertainty of the mean increases when the spacing increases for a given number of samples. Small extents (relative to the underlying correlation length) imply that the samples are highly correlated and the underlying distribution can be well characterized from a limited number of samples. Skøien and Blöschl (2006) used numerically generated random fields, and actual observations of  $K_s$  may differ in terms of their sampling characteristics. Also, by identifying the controls on  $K_s$ , areal estimates can be improved over random sampling, either by stratified sampling or by making use of pedotransfer functions.

The main objective of this paper is to identify the main elements that control the soil saturated hydraulic conductivity in an agricultural setting and, on this basis, to define the minimum number of samples needed for estimating a value of  $K_s$  representative at the plot scale. This is a crucial element to obtain the first of the two moments of the  $K_s$  probability density function required to apply areal infiltration modeling (Flammini et al., 2018). The results of  $K_s$  measurement campaigns performed in a small catchment in Austria with double-ring infiltrometers (DRIs) are used. The choice of this equipment was made on the basis of a few practical considerations later specified and mainly of the outcomes earlier obtained by Morbidelli et al. (2017) in laboratory experiments finalized to compare a double-ring infiltrometer, a tension permeameter and a constant-head well permeameter using controlled rainfall-runoff experiments as a benchmark. Measurements collected in both grasslands and arable lands are selected to deduce the effects of different land management operations on the  $K_s$  spatial variability. A statistical analysis is performed to understand the confidence in the estimate of the areal average value of  $K_s$  for different land uses, plot areas and sample sizes. Based on this analysis, guidance is given for planning measurement campaigns with double-ring infiltrometers when time and resources are limited.

## 2. Materials

### 2.1. Study area

The study area is the Hydrological Open Air Laboratory (HOAL) catchment located in Petzenkirchen, in the western part of Lower Austria. The basin has an area of 0.66 km<sup>2</sup>. The elevation ranges from 268 to 323 m a.s.l. with a mean slope of 8%. Landcover consists of arable land (87%), pasture (5%), forested area with grassland and high-stemmed vegetation of low density (6%), and paved surfaces (2%) (Blöschl et al., 2016). In this study, pasture and forested area are collectively denoted as “grassland areas” because the forested area is really characterized by grassland, and not by brushwood, as a result of the patchy type of land use that takes place in the catchment. The climate is humid with a mean annual temperature of 9.5 °C and a mean annual precipitation of 823 mm yr<sup>-1</sup> from 1990 to 2014.

A soil survey campaign of 300 cores, sampled on a 50 × 50 m grid, provided information about organic matter content (*om*), clay (*cl*), silt (*si*), and sand (*sa*) percentages at multiple depths. According to the USDA soil classification, the topsoil in the catchment consists of silt loam (75% of the area), silty clay loam (20%), and silt (5%). A high-resolution digital terrain model (DTM) was used to derive elevation (*el*) and local slope angles (*s*) across the catchment.

Winter wheat, winter barley, maize, rapeseed and soy are the main types of crop cultivated in the catchment. Crop rotation is associated with green manure in order to ensure natural fertilization of the soil. However, nitrogen fertilizers and natural fertilizers, e.g. pig manure,

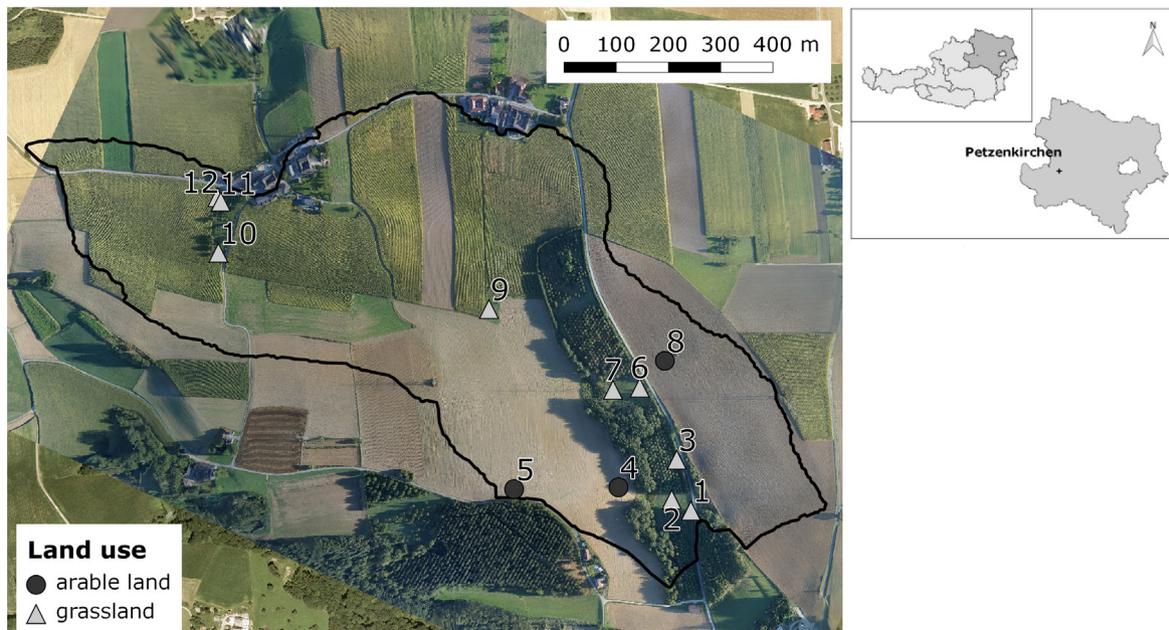


Fig. 1. Measurement plots in the catchment. Dark-grey circles represent plots located in arable areas, light-grey triangles represent plots located in grassland areas. The catchment location in the Lower Austria region is also shown.

are also applied before sowing, as well as plant protection agents, such as plant growth regulators, fungicides and broad-spectrum insecticides. The harvest of the winter crops usually occurs in July, allowing the access to the cultivated areas for infiltration measurements until the late-August/September when field preparation for tillage and seedbed is made.

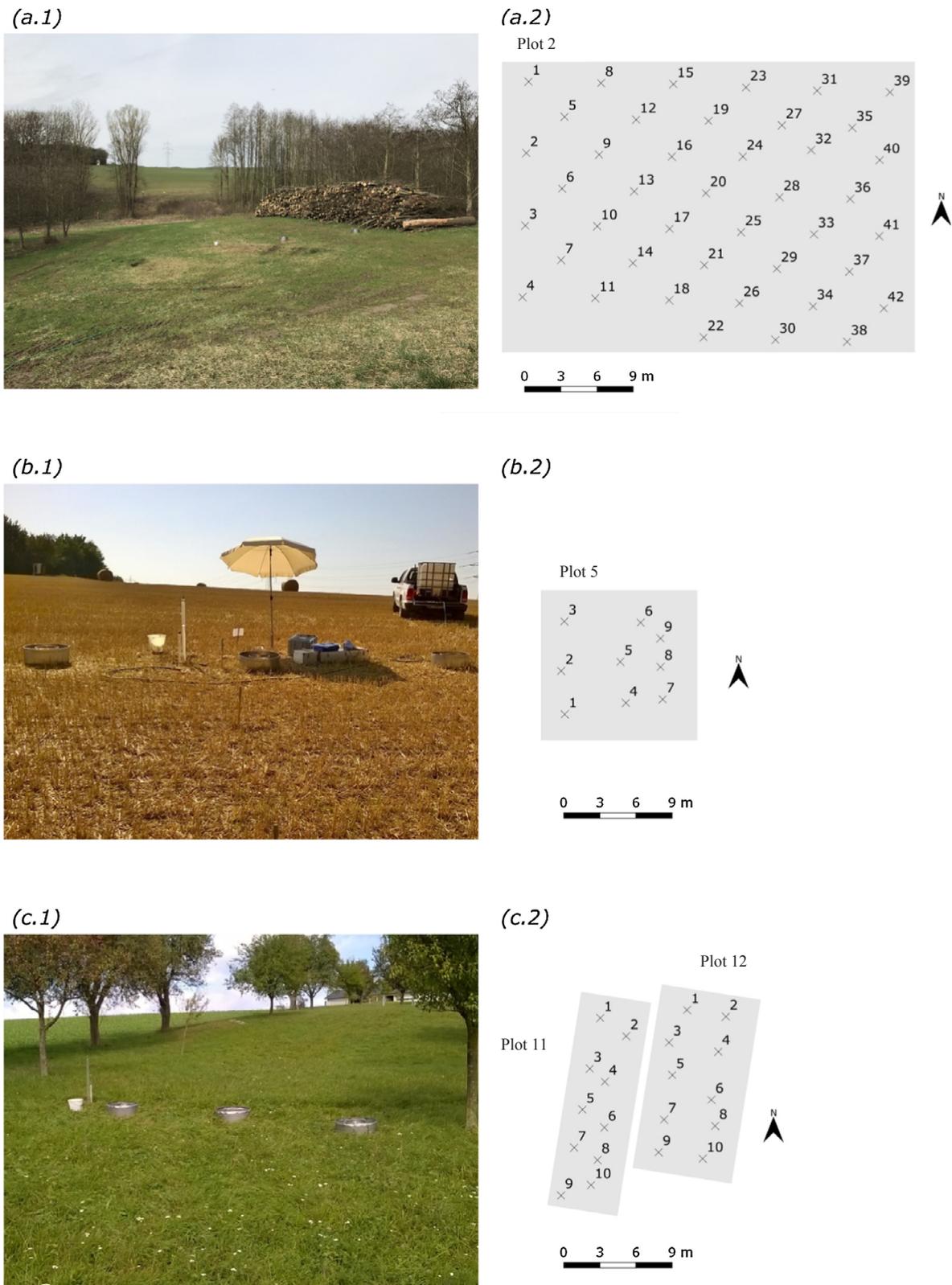
## 2.2. Soil data collection

A total of 131 locations, on 12 different plots, were chosen to sample  $K_s$  of the soil surface of the HOAL catchment (Fig. 1). The measurements were performed with the objective of evenly exploring the grassland areas, specifically those without high-stemmed vegetation, and the areas devoted to agricultural practices. Depending on the time required to perform a local experiment by the selected procedure (described below), the measurements in each plot were carried out in a narrow period, up to 3 days for the larger plot. The measurements in the whole grassland areas were substantially completed in the period March 15–April 7, while in the cultivated areas, due to restricted access during the crop growing season and tillage operations, the experimental campaign was made in the period between harvest and tillage. In the last period, between July 20 and September 20, it was possible to investigate different plots at the same condition with respect to agricultural practices even though at different times. In any case, because of the absence of bare soils subjected to significant temporal changes of  $K_s$  due to crust formation and disruption, the lack of measurements contemporaneity should not have significantly affected the main features of the  $K_s$  spatial heterogeneity field.

Among the available measurement techniques, DRIs were considered to be appropriate because of the ease of installation and robustness in natural environments where tall grass, surface slope or strong wind may preclude the usage of other, more sensitive, devices. Due to the equipment low cost, simultaneous use up to four instruments was possible to speed up the experiments. The technique consists of pushing two concentric steel rings, of diameters 0.3 m and 0.6 m, about 10 cm into the ground and pouring water inside them until the water level equalizes in the two rings. The reduction of the inner ring water level due to infiltration is recorded at regular time steps, and the measurement ends when infiltration steady state is obtained. In our

measurements the latter was considered to occur when an infiltration rate invariant in the last hour was detected. The saturated hydraulic conductivity was assumed equal to the last value of infiltration rate, typically observed with a ponded depth of water of about one centimeter. Morbidelli et al. (2017) showed that DRIs tended to overestimate the areal average value of  $K_s$  as compared to controlled rainfall-runoff experiments. They also found that, when samples were taken with DRI in a highly-controlled laboratory system characterized by a soil with homogeneous grain size distribution and bare surface, the observed values did not significantly change over the repetitions performed in adjacent places. This finding highlights that DRIs allow reliable estimates of  $K_s$  in terms of repeatability, but they are biased compared to the benchmark value. In any case, considering the measurement repeatability, it is expected that the observed bias does not significantly affect the spatial variability analysis of  $K_s$ , even though the possible existence of a bias dependent on the correct  $K_s$  values cannot be ruled out. On the other hand, the magnitude of the bias is still an open issue for any available device because of the difficulties related to the identification of an indisputable “true” reference value of  $K_s$ .

On each plot,  $K_s$  measurements were performed with a spatial resolution of 3 m. The duration of each run was typically of 3–4 h. Fig. 2 highlights examples of the different environmental conditions present on the plots: Fig. 2a, shows the largest plot, plot 2, which consists of grassy land and is located close to the forested area with grassland. Fig. 2b represents plot 5 showing the winter wheat stubbles that remains in the field after the harvest, and Fig. 2c, shows plots 11 and 12, both located in a naturally-vegetated orchard. In the choice of the measurement locations, slope represented a crucial factor. According to Philip (1991), in the initial stage of the infiltration process – when the capillary forces play a leading role – the infiltration rate does not depend on the surface inclination, but after a long time – when only gravitational forces drive the process – the infiltration rate is reduced by the cosine of the slope angle. However, experimental evidence does not always support this theoretical formulation (Essig et al., 2009; Morbidelli et al., 2015). In any case, it is widely recognized that slope affects the infiltration process. In this light to reduce the slope effects (Morbidelli et al., 2016), measurements were only performed at locations with surface slope angles generally less than  $10^\circ$  and in the absence of bare soils.



**Fig. 2.** Pictures of some measurement sites (1) and correspondent scheme of measurements performed (2) for different environmental conditions present in the plots: (a) plot 2, the largest plot located in the proximity of the forested area of the catchment and featuring a grassy meadow land; (b) plot 5, located in the cultivated area of the catchment; (c) plots 11 and 12, both located in a naturally vegetated orchard.

At the locations where the infiltration measurements were performed, soil textural composition and organic matter content were inferred from the survey data available on the 50 × 50 m grid. In addition, slope and elevation across the catchment were obtained from the

DTM. The physical and topographical soil characteristics, displayed in Table 1, show little spatial variation between the measurement locations. The maximum Coefficient of Variation (CV) observed for textural composition and organic matter content is about 15%, consistent with

**Table 1**

General statistics of the physical and topographic soil characteristics available in the same locations where the infiltration measurements were performed. Min = minimum value; Max = maximum value; Mean = arithmetic mean; CV = coefficient of variation; *om* = organic matter content; *cl* = clay content; *si* = silt content (as complementary to 100% of clay and sand); *sa* = sand content; *s* = slope angle; *el* = elevation.

Statistics	<i>om</i> (%)	<i>cl</i> (%)	<i>si</i> (%)	<i>sa</i> (%)	<i>s</i> (°)	<i>el</i> (m a.s.l.)
Min	1.9	17.6	68.7	6.0	2.4	263.1
Max	3.4	23.0	73.8	11.5	13.0	316.4
Mean	2.6	20.3	71.3	8.4	6.1	279.3
St. dev.	0.4	1.1	1.5	1.2	1.9	16.3
CV (%)	13.8	5.6	2.1	14.7	31.7	5.8

the USDA soil classification of the catchment according to which only two main soil types are identified in the basin (95% of the topsoil is either silt loam or silty clay loam). Only the surface slope angle exhibits a significant variation, with a CV of about 30%.

### 3. Method

#### 3.1. Statistical analysis and controls on saturated hydraulic conductivity

The ANOVA method (Armstrong et al., 2000) has been selected for the analysis of variance of the experimental data associated to the different plots to understand whether the variability of  $K_s$  across the catchment is linked to specific soil physical characteristics of the measurement locations. An application of this method requires that specific assumptions on the experimental data are satisfied. In general terms, the results obtained for the study variable are subdivided into  $J$  groups and the  $i$ th observed value ( $i = 1 \dots I$ ) of a given group,  $j$  ( $j = 1, \dots, J$ ), can be expressed as a sum of the mean of all the available measurements,  $\mu$ , the group effect,  $\tau_j$ , representing the deviation of the group mean  $\mu_j$  from  $\mu$  and a random element,  $\varepsilon_{i,j}$ , reflecting the combined effects of measurement errors and natural variation through observations. The basic assumptions involved in the ANOVA method concern the random elements that should be normally distributed with the same variance in all groups, while the means  $\mu_j$  can be variable from group to group. The available  $K_s$  data do not satisfy these two conditions, while log-transformed values of  $K_s$  have been found appropriate for the ANOVA method application (see also Snedecor and Cochran, 1980). The following procedure has been therefore used.

The entire data-set has been divided into  $J$  groups and a single transformed observation,  $\ln(K_s)_{i,j}$ , has been expressed as:

$$\ln(K_s)_{i,j} = \mu + \tau_j + \varepsilon_{i,j} = \mu_j + \varepsilon_{i,j} \quad i = 1, \dots, I; j = 1, \dots, J \quad (1)$$

with  $\tau_j = \mu_j - \mu$  and with the quantities  $\mu_j$  and  $\varepsilon_{i,j}$  computed on the transformed data-set. On this basis, to highlight a possible absence of group effect, the null hypothesis of equality of the  $J$  values of the mean has been tested starting from the quantity  $SS_t$  defined as:

$$SS_t = \sum_i \sum_j (\ln(K_s)_{i,j} - \mu)^2 \quad (2)$$

that can be rewritten as:

$$SS_t = SS_w + SS_b = \sum_i \sum_j (\ln(K_s)_{i,j} - \mu_j)^2 + \sum_j n_j (\mu_j - \mu)^2 \quad (3)$$

where  $SS_w$  is associated to the variation within each group,  $SS_b$  to the variation between each group and the catchment, and  $n_j$  is the number of observations in each group. The sample variance,  $\sigma_t^2$ , the “within variance”,  $\sigma_w^2$ , and the “between variance”,  $\sigma_b^2$ , have been then estimated by dividing each term of Eq. (3) by the corresponding degree of freedom:

$$\sigma_t^2 = \frac{SS_t}{df_t} = \frac{SS_t}{I - 1} \quad (4)$$

$$\sigma_w^2 = \frac{SS_w}{df_w} = \frac{SS_w}{I - J} \quad (5)$$

$$\sigma_b^2 = \frac{SS_b}{df_b} = \frac{SS_b}{J - 1} \quad (6)$$

and the variance ratio,  $F$ , has been computed as:

$$F(J - 1, I - J) = \frac{\sigma_b^2}{\sigma_w^2} \quad (7)$$

For testing the null hypothesis,  $F$  has been compared to the critical value,  $F_{crit}(df_b, df_w)$ , obtained from an  $F$ -distribution (Snedecor and Cochran, 1980) with  $df_w$  and  $df_b$  degrees of freedom with a significance level of 5%. If  $F$  is greater than the critical value, the null hypothesis of zero group effect has to be rejected and at least one of the  $\mu_j$  values is significantly different from the grand mean.

The above approach has been applied to different group ensembles: (1) ensemble obtained considering the plot locations as sources of variation to understand whether  $K_s$  variability is substantially linked to the specific physical and topographical characteristics of the measurement areas; (2) ensemble identified grouping areas with the same land use, considered because the outcomes of step (1) suggested a significant dependency of  $K_s$  variability on the plot location; (3) ensembles of plots characterized by the same land use to understand if (a) other plot-specific properties had a significant influence or (b) the observations could be considered as different sets sampled from the same population, even though collected at different locations in the catchment.

#### 3.2. Uncertainty analysis and minimum number of samples needed

An analysis has been performed with the aim of determining the uncertainty related to the estimate of an average  $K_s$  value for a specific area. The  $K_s$  geometric mean,  $\bar{K}_s$ , has been chosen as the representative estimator of the areal average saturated hydraulic conductivity. Obviously, the higher the number of measurements used to estimate the geometric mean of  $K_s$ , the higher is the confidence that the estimate is representative of the true value of  $\bar{K}_s$  for the considered area. However, since the measurements are very time consuming, understanding whether it is possible to reduce the number of measurements and still obtain a reliable average, would enormously improve the planning of measurement campaigns with reduced realization times.

A well-founded uncertainty analysis based on the use of the confidence intervals has been carried out. It is rather similar to that used by Ahmed et al. (2015) with changes directed to improve the interpretation of results. The plots 2, 11–12, and 7 have been selected because they exhibited the same sampling density (about 1 measurement every 10 m<sup>2</sup>), the same land cover (grass) but different number of observation points, i.e., 40, 20 and 9, respectively. For each data-set the non-parametric bootstrap method (Carpenter and Bithell, 2000) has been used to estimate confidence intervals around the geometric mean for different numbers of samples. The method is particularly helpful whenever confidence intervals must be calculated for small data-sets, as in the case of plot 7 where only 9 measurements are available. As suggested by Carpenter and Bithell (2000), information about the value of a population parameter (e.g. the mean,  $\mu$ ) can be obtained by drawing a random sample  $\mathbf{Y}$  from that population and constructing an estimate  $\hat{\mu}(\mathbf{Y})$  of the value of  $\mu$  from that sample. The bootstrap principle is adopted to achieve information about the relationship between  $\mu$  and  $\hat{\mu}(\mathbf{Y})$  by looking at the relationship between  $\hat{\mu}(\mathbf{y}_{obs})$  and  $\hat{\mu}(\mathbf{Y}^*)$ , where  $\mathbf{Y}^*$  is a resample characterized by the sample of the observations  $\mathbf{y}_{obs}$ . Because the method involves a resampling step – which can be done assuming a specific distribution for the parameter and sampling from it (i.e. parametric bootstrap) or without assuming any distribution for the parameter and sampling with replacement (i.e. non-parametric bootstrap) – it is often used for small data-sets.

In implementing the bootstrap method, the observations have been

assumed independent, sampling has been done with replacement and the process has been repeated 1000 times, as suggested for the 95% confidence interval by Carpenter and Bithell (2000). From each subsample the geometric mean has been estimated. A set of 1000 geometric mean values has been obtained and the 95% confidence interval has been derived by calculating the 2.5 and 97.5 percentiles. The procedure has been repeated changing the number of observations ( $n$ ). For each plot, the trend of the confidence interval has been derived varying the number of observations  $n$  from 2 to the maximum number of data available. The three trends obtained have been then normalized by the geometric mean of  $K_s$  of each plot to facilitate visual comparisons.

A further analysis has been performed using plot 2 to determine for different plot areas the minimum number of measurements requested to derive  $K_s$ . This plot was the one with the largest data-set. Six sub-areas of 55, 110, 165, 215, 280 and 345 m<sup>2</sup> have been considered, with larger sub-areas always containing all the smaller ones. In each sub-area, 4, 5, 6, 7, 8 and 9 measurements have been drawn, and the 95% confidence intervals have been estimated as above specified for a total of 36 combinations area - sample number. Finally, the widths,  $A_{95}$ , of the confidence intervals calculated as the difference between the 97.5 and 2.5 percentiles, have been plotted against area for different sample numbers. The curves describe how the confidence in the estimation of  $K_s$  decreases when an equal number of measurements are performed on plots of increasing dimensions or how many samples are needed to obtain a given accuracy.

## 4. Results and discussion

### 4.1. Controls on the spatial variability of saturated hydraulic conductivity

Fig. 3 suggests that soil physical characteristics do not have a direct effect on  $K_s$  variability. A wider  $K_s$  variation range seems to be related to lower  $om$  (Fig. 3a), higher  $si$  (Fig. 3c) or lower  $sa$  (Fig. 3d), however this may be caused by the variation of the physical characteristics with land use, rather than by a direct dependency of  $K_s$  on texture. Most likely, considering that arable areas are characterized by lower percentages of  $om$  and  $sa$ , and higher percentage of  $si$ , the corresponding wider variation range could be an expression of the treatment effect due to land use (investigated later), instead of a reflection of changes in soil textural composition. The weak relationship between  $K_s$  and soil textural composition is in contrast with experimental evidence of a strong connection between  $K_s$  and particle size distribution (Rahmati et al., 2018), and is likely related to the small variation of soil characteristics in the catchment. On the other hand,  $K_s$  is somewhat dependent on the slope angle (Fig. 3e). In particular, higher values of  $K_s$  were observed at close to horizontal areas, while the  $K_s$  range decreases with increasing slope angle  $s$ . The relationship between slope angles and the textural components is shown in Fig. 4. No clear dependency of  $s$  on any of the considered soil characteristics can be detected, therefore, the influence of  $s$  on  $K_s$  is not related to changing soil attributes with slope but could be due to variations in soil properties not captured by texture. In this context differences in soil packing and presence of macropores, both influenced by random components that cannot be objectively quantified, should have generally a major role and explain also the  $K_s$  heterogeneity within each plot. On the other hand, it is not expected that the significant decrease of  $K_s$  with increasing  $s$ , highlighted by Morbidelli et al. (2015, 2016) under conditions of surface water moving downslope, can be deduced by measurements of  $K_s$  performed with classical devices in the absence of overland flow.

Notwithstanding the limited spatial variation of the physical and topographical soil attributes, saturated hydraulic conductivity varies substantially, with values ranging over two orders of magnitude, from a minimum of 1 mm h<sup>-1</sup> to a maximum of 130 mm h<sup>-1</sup> (Table 2). The high spatial variability of  $K_s$  is a well-known characteristic of this parameter, regardless of the measurement technique applied, the

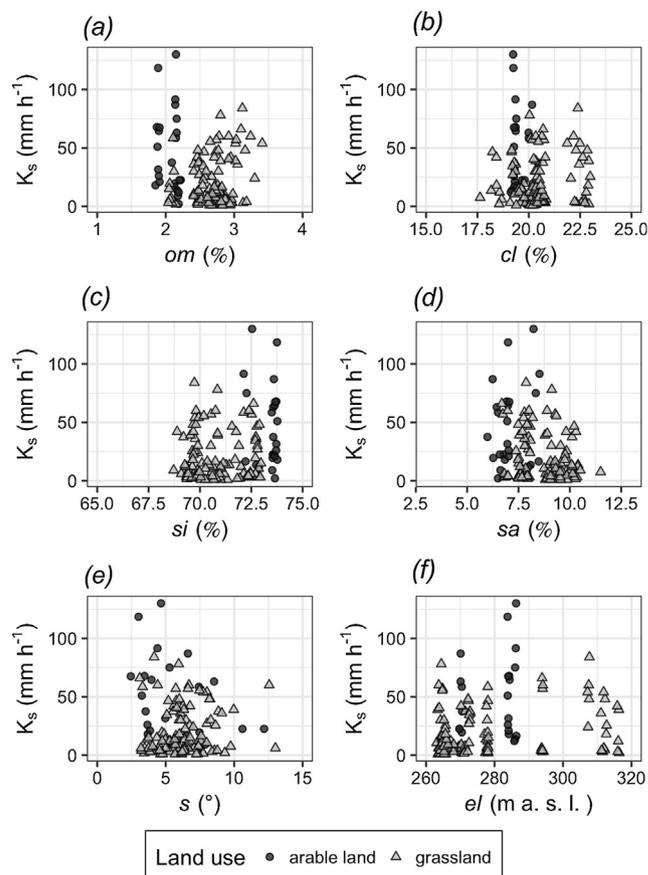


Fig. 3. Saturated hydraulic conductivity,  $K_s$ , observations plotted against (a) organic matter content,  $om$ ; (b) clay content,  $cl$ ; (c) silt content,  $si$ ; (d) sand content,  $sa$ ; (e) slope angle,  $s$ ; (f) elevation,  $el$ . Dark-grey circles represent plots located in arable areas, light-grey triangles represent plots located in grassland areas. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

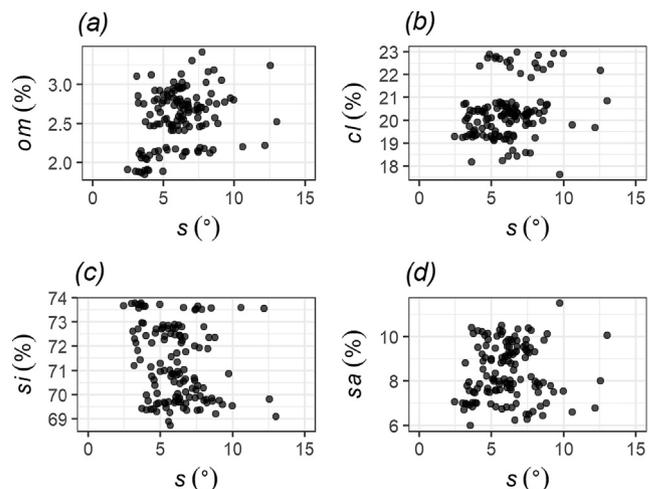


Fig. 4. Slope angles plotted against (a) organic matter content,  $om$ ; (b) clay content,  $cl$ ; (c) silt content,  $si$ ; (d) sand content,  $sa$ .

geographical location, the land use or the soil type (Baïamonte et al., 2017; Papanicolaou et al., 2015), therefore, this parameter is considered as a random variable depending also on random factors that cannot be quantified.

Table 2 further shows the differences in the  $K_s$  variability between arable and grassy plots. The  $K_s$  minimum and maximum observed in

**Table 2**

General statistics of the  $K_s$  values measured with double-ring infiltrometer. Min = minimum value; Max = maximum value; Mean = arithmetic mean; CV = coefficient of variation; Skew = skewness; Mean log = arithmetic mean of the log-transformed values; CV log = coefficient of variation of the log-transformed values; Arable land =  $K_s$  values measured in arable areas; Grassland =  $K_s$  values measured in grassy areas; Total = all  $K_s$  values.

Statistics	Arable land	Grassland	Total
Min ( $\text{mm h}^{-1}$ )	2.0	1.0	1.0
Max ( $\text{mm h}^{-1}$ )	130.0	84.0	130.0
Mean ( $\text{mm h}^{-1}$ )	46.9	20.2	25.1
St. dev. ( $\text{mm h}^{-1}$ )	35.5	20.3	25.8
CV (%)	75.6	100.3	102.7
Skew (-)	0.8	1.1	1.5
Median ( $\text{mm h}^{-1}$ )	34.5	12.0	15.0
Mean log (-)	3.5	2.4	2.6
CV log (%)	27.7	50.6	47.9

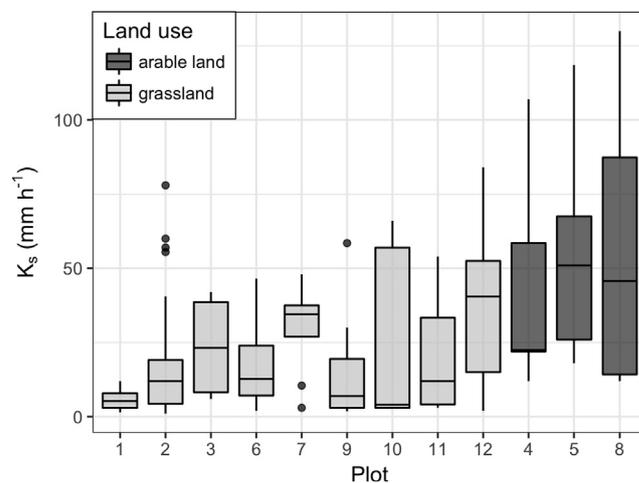
arable lands are significantly larger than those obtained in grassy plots with values increased more than 50%. This result can be explained by the fact that, after the harvest, i.e. the condition in which the infiltration measurements were performed, the whole root system of winter crops including stubbles was present. Therefore, the presence of the root system, typically very deep (see f.i. Thorup-Kristensen et al. (2009) for winter wheat), allowed the establishment of a preferential flow regime more efficient than that of grassy soils, where the maximum depth of the root system was much lower, with values of a few tens of centimeters (see also Brown et al., 2010; Morbidelli et al., 2014). In addition, the behavior of the arable lands is justified by the regular mixing/loosening of the plough layer that takes place twice a year, either through ploughing or chiseling, with the result that the pore size distribution can be characterized by more medium pores and less fine pores than grassland. On the other hand, the grassy plots do not exhibit a plough layer but distinct hydromorphic features more or less close to the surface. The uniform distribution of the root system that remains in the field, coupled with the periodic land management of the investigated soils, is also responsible for a more homogeneous distribution of  $K_s$  across the area. The lower variability is reflected by the coefficient of variation that in the arable fields assumes values reduced of about 25% with respect to those associated to the grassland areas. Land management operations repeated season after season, such as tillage or plowing, in addition to a uniform land cover of crops having the same growing period and therefore similar depths of the root system appear to reduce spatial variations due to different plant varieties and soil transformation mechanisms affecting the land surface, e.g. soil compaction, crust formation or soil swelling.

A site-by-site examination reveals very similar minima of saturated hydraulic conductivity on almost every plot (Table 3). On the other hand, the maxima vary greatly between different plots. On each plot, the coefficient of variation assumes values  $CV \geq 0.5$  that closely reflect the value associated to the entire catchment. This indicates that the high  $K_s$  spatial variability is still traceable when the observation plots

**Table 3**

General statistics of the  $K_s$  values, grouped by plot. n. obs. = number of observations in each plot; Min = minimum value; Max = maximum value; Mean = arithmetic mean; CV = coefficient of variation; G. mean = geometric mean.

Plot	1	2	3	4	5	6	7	8	9	10	11	12
n. obs.	8	40	4	9	9	8	9	6	9	9	10	10
Min ( $\text{mm h}^{-1}$ )	1.5	1.0	6.0	2.0	18.0	2.0	3.0	12.0	1.8	3.0	3.0	2.0
Max ( $\text{mm h}^{-1}$ )	12.0	78.0	42.0	87.0	118.5	46.5	48.0	130.0	58.5	66.0	54.0	84.0
Mean ( $\text{mm h}^{-1}$ )	5.8	17.0	23.6	35.7	51.8	18.4	30.3	56.4	16.0	22.9	20.2	36.8
St. dev. ( $\text{mm h}^{-1}$ )	3.5	18.6	18.8	28.2	32.2	16.7	15.1	49.8	18.5	28.7	19.7	26.6
Median ( $\text{mm h}^{-1}$ )	5.3	12.0	23.3	22.5	51.0	12.8	34.5	45.8	7.0	4.0	12.0	40.5
CV (%)	60.8	109.0	79.4	78.9	62.2	90.6	49.8	88.3	115.7	125.3	97.6	72.2
G. mean ( $\text{mm h}^{-1}$ )	4.8	9.1	17.1	23.4	43.5	12.3	24.0	36.6	8.9	9.4	11.5	22.7



**Fig. 5.** Boxplots of saturated hydraulic conductivity,  $K_s$ , for the different measurement plots. Dark-grey boxplots represent plots located in arable areas, light-grey boxplots represent plots located in grassland areas. The box represents the interquartile range, i.e. difference between the third and the first quartiles. The horizontal black line represents the median of each plot. The dark-grey dots, usually representing possible outliers, were nevertheless considered as acceptable occurrences of  $K_s$  as they lie in the typical  $K_s$  domain. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

are individually considered. More information about plot differences and similarities is provided by Fig. 5, which shows the boxplots of  $K_s$  on each measurement plot. As mentioned before, the minima vary little between plots, while the maxima vary a lot. There are differences related to land use: the first quartile in grassy fields (except plot 7) is less than or equal to the minima observed on arable plots 5 and 8, indicating that at least 25% of the  $K_s$  values observed in natural conditions is lower than the minimum values observed when agricultural practices become operative. Moreover, about 50% of the  $K_s$  values observed on arable plots 5 and 8 are greater than the maximum values (excluding values that seem to be possible outliers even if for all the analyses they have been considered because included in the  $K_s$  observed range) measured on grassy plots 1, 2, 3, 6, 7 and 9 due to the fact that the median is greater than or equal to the maximum of each mentioned grassy plot. The boxplot analysis highlights a significant variability among the different measurement plots but it does not clarify if the detected variation is caused by specific physical and topographical characteristics, by different land uses or simply by the random nature of saturated hydraulic conductivity.

In order to understand whether the variability of  $K_s$  across the catchment is more related to the random nature of the parameter than to the measurement location or vice versa, an analysis of the variance has been carried out. The first step of the analysis has been therefore aimed at determining whether the plot characteristics have a significant influence on  $K_s$  spatial variability. The whole set of measurements has

**Table 4**

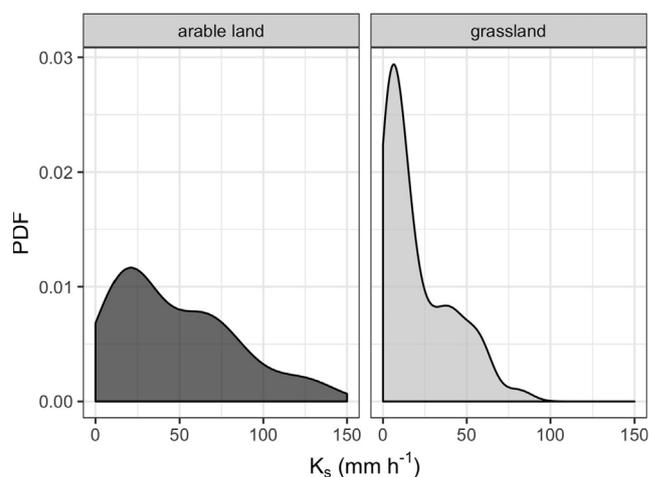
Results of ANOVA analyses. df = degree of freedom ( $df_b$ ;  $df_w$ ;  $df_t$ ); SS = sums of squares ( $SS_b$ ;  $SS_w$ ;  $SS_t$ );  $\sigma^2$  = variance ( $\sigma_b^2$ ;  $\sigma_w^2$ ); F = variance ratio;  $F_{crit}$  = critical value of the F-ratio. All variances (SS,  $\sigma^2$ ) relate to the logarithms of  $K_s$ .

Source of variation	df	SS	$\sigma^2$	F	$F_{crit}$
<b>(a) All measurements grouped by plot</b>					
Plot (between)	11	44.7	4.1	3.1	1.9
Error (within)	119	156.9	1.3		
Total	130	201.5			
<b>(b) All measurements grouped by land use</b>					
Land use (between)	1	23.7	23.7	17.2	3.9
Error (within)	129	177.8	1.4		
Total	130	201.5			
<b>(c) Grassland measurements grouped by plot</b>					
Plot (between)	8	19.1	2.4	1.7	2.0
Error (within)	98	137.0	1.4		
Total	106	156.2			
<b>(d) Arable land measurements grouped by plot</b>					
Plot (between)	2	1.8	0.9	1.0	3.5
Error (within)	21	19.9	0.9		
Total	23	21.7			

been divided into  $J = 12$  groups, representing the twelve measurement plots. Table 4a shows the results of the analysis of variance which has been carried out on the log-transformed data. The ANOVA assumptions of normally distributed residuals and homoscedasticity have been tested with the Shapiro-Wilk test (Shapiro and Wilk, 1965) and the Breusch-Pagan test (Breusch and Pagan, 1979), respectively. The variance between different plots,  $\sigma_b^2 = 4.1$ , is almost three times higher than the variance within each plot,  $\sigma_w^2 = 1.3$ . This means that the largest share of variability is traceable to the physical, topographical and land cover differences between the plots. An additional evidence resides in the fact that the value of F, equal to 3.1, is greater than the critical value of 1.9, and therefore the null hypothesis of absence of treatment effect, i.e. the effect of plot location in the present case, must be rejected.

In the interest of further analyzing the origin of the treatment effect, the main variability source represented by the land use has been considered. The whole set of  $K_s$  observations has been divided into arable and grassland areas ( $J = 2$ ), regardless of the specific type of crop cultivated in the field and the type of natural vegetation. Table 4b shows the ANOVA results when land use is considered as source of variability. The variance associated with the measurement error and the random nature of  $K_s$ , i.e.  $\sigma_w^2$ , is 1.4, and is thus almost negligible compared to  $\sigma_b^2 = 23.7$  indicating that land use is most likely the main driver for the observed  $K_s$  variations across the catchment. The value of the F-ratio of 17.2 is much larger than the critical F of 3.9 associated with a significance level of 5%, indicating that the group effect is not negligible and the means of the two groups are significantly different from each other.

Finally, since both land use and measurement plot location are responsible for a non-negligible treatment or group effect, it is interesting to understand if both factors cause saturated hydraulic conductivity to vary in space, or rather if the two are related with each other and  $K_s$  spatial variability is actually due to only one of them. In other words, we want to understand if  $K_s$  varies with plot location because of different physical and topographical soil characteristics specific of each plot or only because every plot exhibits a different land use. To this end, the whole sample of  $K_s$  observations has been split into two sub-samples – the first one consisting of measurements performed in grassland areas and the second of measurements performed in arable areas – and within each sub-sample an analysis of variance has been carried out considering as source of variation the plot location. Results of the analyses are shown in Table 4c and d. In both cases, variances associated with treatment (between) and error (within) have approximately the same



**Fig. 6.** Probability Density Functions (PDFs) of observed saturated hydraulic conductivity,  $K_s$ , values on both arable (dark-grey) and grassy (light-grey) fields. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

values, and the F-ratio is always lower than the critical value. These results indicate that plot location does not explain the spatial variability and that measurements on different plots with the same land use can be considered as sampled from the same population because the null hypothesis of equality of each group mean to the grand mean cannot be rejected.

The great influence of land use on the observed  $K_s$  variability is evident when two Probability Density Functions (PDFs) of  $K_s$  are associated to observations divided into the two sub-samples previously defined. Saturated hydraulic conductivity, that is usually assumed as log-normally distributed (Sharma et al., 1987; Dagan and Bresler, 1983), is characterized by the PDFs of both grassy and arable fields which tend to be bimodal but can be in any case well approximated by log-normal distributions, as tested with the Shapiro-Wilk test (Shapiro and Wilk, 1965) on the log-transformed data. In addition, as shown in Fig. 6, they exhibit different shapes. In arable fields, the PDF is flatter, the peak is lower and less pronounced, the variation range is larger and the median is  $34.5 \text{ mm h}^{-1}$  as compared to  $12 \text{ mm h}^{-1}$  in grassy fields (Table 2). This means that agricultural practices and a homogeneous land cover influence the random nature of saturated hydraulic conductivity, which still varies randomly inside each group. Clearly, land use strongly influences  $K_s$  in agricultural settings and data collected in arable and grassland areas should not be considered as deriving from the same population.

#### 4.2. Minimum number of samples for estimating areal average saturated hydraulic conductivity

The uncertainty analysis aimed at determining the minimum number of samples required for estimating a reliable  $K_s$  geometric mean,  $K_s$ , for a specific area has been carried out using the data from plots 2, 11–12 and 7. These plots had the same land use, different areas (about  $500 \text{ m}^2$ ,  $200 \text{ m}^2$  and  $80 \text{ m}^2$ , respectively) and different number of total observations. However, considering that the measurements were performed with the same spatial resolution, the plots approximately had the same measurement density (about 1 observation per  $10 \text{ m}^2$ ). Fig. 7 shows the 95% confidence interval of  $K_s$  normalized by its geometric mean of the specific plots. For a specific number of measurements,  $n$ , the plot with smaller area results in a narrower normalized confidence interval. For example, for  $n = 6$ , the width of plot 7 normalized confidence interval of 1.2 is much narrower than those of plots 2 and 11–12 (2.2 and 2.0, respectively).

Although the normalization influences the width of the confidence

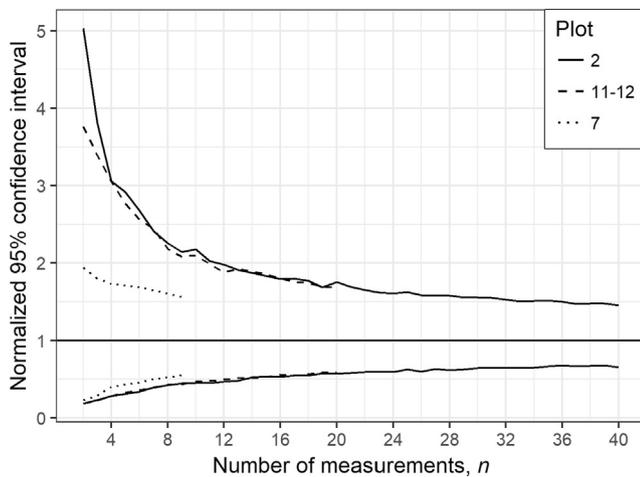


Fig. 7. Normalized 95% confidence intervals of the saturated hydraulic conductivity geometric mean  $K_s$  obtained via non-parametric bootstrap method for 3 grassy plots.

interval because of the different values of the geometric mean of the three plots (Table 3), it does not affect the results in terms of the reliability exhibited by the same value of  $n$  with changing areas. Specifically, for  $n = 6$  the widths of the confidence intervals without normalization by the geometric mean have different trends (29.7, 34.8 and 21.3  $\text{mm h}^{-1}$  for plots 7, 11–12 and 2, respectively), but the corresponding average relative errors of the geometric means of the three plots (62, 107 and 117%, respectively) confirm a higher reliability of the geometric mean estimates for smaller areas. These outcomes are likely related to the lower variability captured in grassy fields when a smaller area is sampled while, in larger areas, local soil heterogeneities (e.g. macropores, wormholes, cracks, local slope) have a higher chance to be encountered. Furthermore, the differences appear to be fairly limited if plots 11–12 and 2 are compared in terms of both the width of the normalized 95% confidence interval (Fig. 7) and the average relative errors. This suggests that, beyond a certain extent, all the local soil heterogeneities characterizing the plot are captured.

This study does not involve a specific analysis of spatial correlations because of the relatively low number of samples on the smaller plots. The hypothesis of independent observations, upon which the bootstrap method is based, was adopted following Ahmed et al. (2015).

Based on the hypothesis of independent data, the confidence interval of plot 2, characterized by a sample statistically significant for the analysis of the frequency distribution, has been also computed adopting a Gaussian distribution for the log-transformed  $K_s$  data. Its trend is shown in Fig. 8 together with that provided by the non-parametric bootstrap method applied to log-transformed  $K_s$  data. As expected, no significant differences can be observed.

Fig. 9 shows the reduction of the confidence interval with increasing the number of measurements for the three plots. The reduction has been obtained as the difference between the width of the non-normalized confidence interval associated with  $n$  measurements and the width associated with  $n - 1$  measurements. On each plot, the reduction is large for small  $n$ . For example, if 4 measurements are used to calculate the confidence interval instead of 3, the width of the confidence interval decreases by 5, 7 and 4.3  $\text{mm h}^{-1}$  for plots 2, 11–12 and 7, respectively. On the other hand, as  $n$  increases, the reduction decreases and tends asymptotically towards zero. This is particularly evident from the interpolated curve of plot 2, even though the same behavior is detected for plots 11–12 and 7. From this it can be deduced that the benefit – in terms of width reduction – gained by performing one extra measurement on each plot is high for small  $n$  and decreases with plot extent up to a point, specific for each plot, where the average reduction rate becomes almost constant, i.e. the interpolated curve becomes

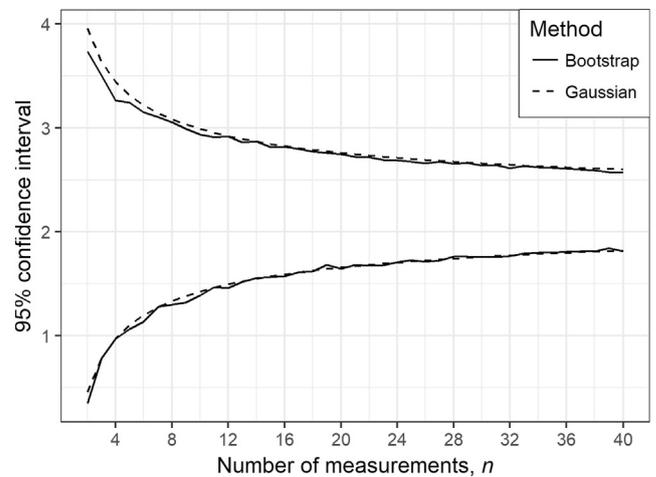


Fig. 8. 95% Confidence interval of the saturated hydraulic conductivity geometric mean obtained applying the non-parametric bootstrap method (solid curve) and for a Gaussian variable (dashed curve). Plot 2, log-transformed data.

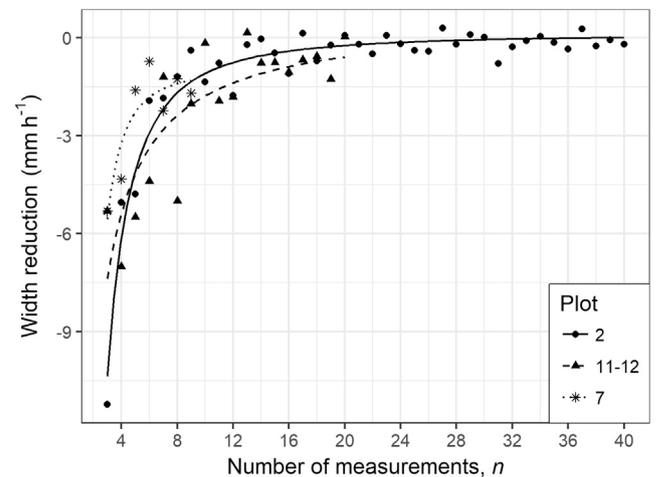


Fig. 9. Reduction of the width of the non-normalized confidence interval of the saturated hydraulic conductivity geometric mean obtained using one extra measurement in the bootstrap method. For a specific  $n$  the corresponding point represents the difference between the width associated with  $n$  measurements and with  $n - 1$  measurements.

horizontal. Therefore, the  $n$  associated with this point can be considered as the minimum number of measurements necessary to enter the “zone” where the confidence interval is stable. For example, the interpolated curve of plot 2 is almost constant for  $n$  greater than 12, suggesting that the reduction of the confidence interval width for more than 12 measurements is negligible.

A further remark concerns the possible influence of spatial correlations on the analysis. The presence of spatial correlations would have the effect of reducing the width of the confidence interval for a specific  $n$  as compared to uncorrelated data (“single realization case” of Sköien and Blöschl, 2006). The same confidence in the estimates of the geometric mean would be therefore achieved with a smaller number of observations. Consequently, the minimum number of measurements would depend on the spatial correlation structure of the investigated plot which would make the application of our results to other areas difficult. On the other hand, the assumption of independent data allows to transfer the results regardless of the plot correlation structure, even though they may represent an upper limit of the density of required measurements if correlations are present.

In order to gain insight into the relationship between grassy and arable fields in terms of accuracy in the  $K_s$  estimation, the same

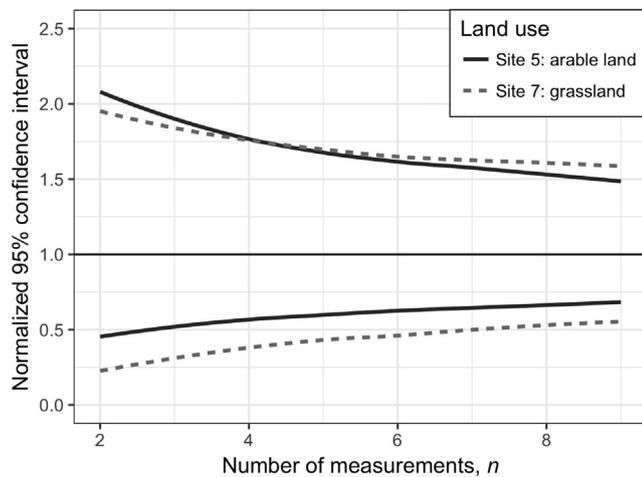


Fig. 10. Normalized 95% confidence intervals by the  $K_s$  geometric mean, obtained via the non-parametric bootstrap method for a grassy and an arable plot. The x-axis represents the number of measurements used for each plot.

uncertainty analysis has been carried out on plots 5 and 7, which possess the same number of observations, the same area, but different land use. Fig. 10 shows that the confidence intervals for the grassland areas are wider than for the arable areas, independently of the number of measurements  $n$  used for the derivation, which is due to the larger variability of  $K_s$  highlighted in the spatial analysis of Section 4.1 for the grassland areas. This result justifies the choice of focusing the consecutive analysis only on grassy fields, because, for the same plot size, the minimum number of measurements derived for natural conditions always ensures a greater accuracy in arable environments.

In planning a field campaign one must decide the number and the location of the measurements in relation to the time required to collect a single observation and the time available. The second step of the uncertainty analysis is aimed at assisting in this choice. In order to be able to compare the combined effect of plot size and number of measurements on the accuracy of the final areal estimation of  $\bar{K}_s$ , six sub-plots have been derived from plot 2 in an attempt to avoid effects of temporal variation of  $K_s$  on the investigated spatial variability. Ideally, the only distinguishing aspects of the sub-plots are size and total number of measurements available. For each sub-plot the 95% confidence intervals of  $\bar{K}_s$  normalized by the geometric mean of the specific sub-plot has been generated through the non-parametric bootstrap method. The width of the normalized 95% confidence interval,  $A_{95}$ , obtained with a specific number of measurements  $n$  as a function of the plot size is shown in Fig. 11. On a plot of specific dimensions, a better estimate of the average saturated hydraulic conductivity can be achieved by increasing the number of measurements in the area, in accordance with the findings of Skøien and Blöschl (2006). For example, if a plot of 165 m<sup>2</sup> is sampled at 5 locations, the width of the confidence interval is about twice the average  $K_s$ , but if 8 measurements are made on the same plot the width is halved (slightly less than  $1 \cdot \bar{K}_s$ ), i.e. the reliability associated with the  $K_s$  estimation is almost doubled. On the other hand, when the same number of samples is taken in increasing areas, the width of the confidence interval increases as well, indicating how the samples progressively lose the ability of representing the true value of  $\bar{K}_s$ . If 7 measurements are performed over an area of 110 m<sup>2</sup>, the width of the confidence interval is  $1.1 \cdot \bar{K}_s$ , but the uncertainty almost doubles whenever the same number of samples is taken on a plot of 345 m<sup>2</sup> ( $A_{95} = 2.1 \cdot \bar{K}_s$ ).

As mentioned before, the confidence intervals are obtained with the non-parametric bootstrap method which is based on the hypothesis of independent data. Although the increase in uncertainty with increasing areas could be partially due to a progressive decorrelation, this is not

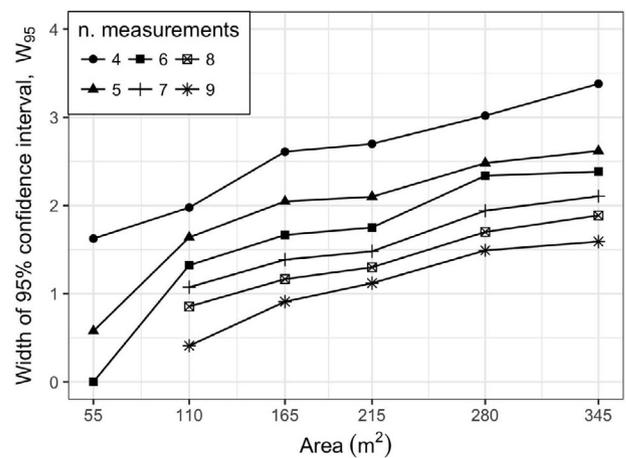


Fig. 11. Width of the 95% confidence intervals normalized by the saturated hydraulic conductivity,  $K_s$ , geometric mean plotted against plot size. Lines represent the number of measurements used for the evaluation of the confidence interval and the geometric mean.

the case because in the derivation of the confidence intervals spatial correlations are not considered. One possible explanation may be the increased likelihood of encountering soil local heterogeneities in larger areas. Additionally, if one considers a sub-area of plot 2 of 120 m<sup>2</sup> the contained measured  $K_s$  are characterized by a variance of about 170 mm<sup>2</sup> h<sup>-2</sup>. When the sub-area is extended up to 300 m<sup>2</sup> the variance increases as well and it is equal to 350 mm<sup>2</sup> h<sup>-2</sup>. Finally, if the sub-area is further extended up to 450 m<sup>2</sup> the variance reaches the value of 410 mm<sup>2</sup> h<sup>-2</sup>, and for greater areas the variance value fluctuates in the range 350–400 mm<sup>2</sup> h<sup>-2</sup>. This trend confirms that when the sampled area increases more variability is encountered and therefore the uncertainty on the estimation of the  $K_s$  geometric mean value increases as well.

Fig. 11 is also useful to derive a minimum number of samples that have to be taken in an area of specific dimensions for a tradeoff between accuracy (or uncertainty) and time required for the measurements. Selection of the accuracy level should consider the typical  $\bar{K}_s$  value of the study since the average error is relative to it. For example, if  $A_{95}$  is assumed equal to 1.5 for a silty loam soil, for which a typical  $K_s$  value of about 1.6 mm h<sup>-1</sup> is expected (Corradini et al., 1997), the estimated value of  $\bar{K}_s$  can vary on average between 0.4 and 2.8 mm h<sup>-1</sup>. However, if the same width is chosen for a sandy loam soil, for which a typical  $K_s$  value of about 25 mm h<sup>-1</sup> is expected (Corradini et al., 1997), the estimated value of  $\bar{K}_s$  will vary on average between 6.25 and 43.75 mm h<sup>-1</sup>. Furthermore, the level of accuracy should be selected in relation to the final purpose of the measurement campaign. For instance, if the peak discharge of a stream has to be estimated by a rainfall-runoff model for designing a weir system along the stream, the required accuracy of  $\bar{K}_s$  could be inferred from the required accuracy of the flood estimate by error propagation.

The accuracy level suggested by Ahmed et al. (2015) varies in the range of 1.8–2.2. When the reference value is taken as 1.8, Fig. 11 suggests that for a plot of 110 m<sup>2</sup> at least 5 measurements are needed to obtain a width of the normalized 95% confidence interval equal to or smaller than the reference value. Similarly, on a plot of 280 m<sup>2</sup> at least 8 samples should be taken in order to estimate average saturated hydraulic conductivity.

## 5. Conclusions

In this study 131 saturated hydraulic conductivity measurements were performed in a small Austrian watershed with double-ring infiltrometers. This device was chosen due to the measurement

repeatability, low cost, which allowed parallel measurements, and ease of installation and operation in natural environments. Measurements were carried out on 12 plots, with a 3 m spatial resolution, trying to avoid local macroporosity and preferential flow paths as well as agricultural machinery tracks. Observations were collected in both grassland and arable areas to account for land cover effects on the variability of  $K_s$ .

While soil texture is not significantly variable in the catchment,  $K_s$  varies by two orders of magnitude, with a minimum of  $1 \text{ mm h}^{-1}$  and a maximum of  $130 \text{ mm h}^{-1}$ . The variation range in arable areas is wider than in grassland (pasture, forest) areas. The minima are similar, but the maximum value of  $K_s$  in cultivated plots is 50% greater than those in the grassy plots. Soil management practices and uniform land cover are considered the main causes of the lower spatial variability of  $K_s$  in the cultivated areas, where CV assumes values reduced of about 25% with respect to those obtained in the areas with natural vegetation.

An analysis of variance has been also carried out with the purpose of understanding the role of plot characteristics, including land cover, on the variability of saturated hydraulic conductivity. The results show that the main control is the land cover and the plot location influences  $K_s$  only because different plots are characterized by different land uses. The great influence of land cover is also reflected by the probability density functions considered separately for grassland and arable areas. Although both PDFs follow a log-normal distribution, their shapes are rather different, with a median of  $12 \text{ mm h}^{-1}$  in grassy fields and  $34.5 \text{ mm h}^{-1}$  in arable fields. Therefore, two separate PDFs should be considered to characterize the probability distribution of  $K_s$  measurements performed with a double-ring infiltrometer in natural or agricultural settings.

Finally, an uncertainty analysis has been performed aimed at determining the minimum number of measurements necessary for estimating the geometric mean of  $K_s$  for a specific area. From the analysis of three grassy plots with the same measurement density, it is clear that the uncertainty, expressed in terms of width reduction of the 95% confidence interval, decreases rapidly as the number of measurements increases up to a certain value. Here the reduction stabilizes and, after this point, the increasing of the number of observations used in the estimate provides little benefit in accuracy compared to the cost, in terms of time and resources, of each additional measurement. The width of the confidence interval obtained with a specific number of measurements increases with plot size most likely because of the higher chance to encounter soil local heterogeneities such as macropores, wormholes, different root systems or preferential flow paths. The increase appears to be limited beyond a certain extent, suggesting that all the local soil heterogeneities characterizing the plot are captured, even though further analyses on this should be made.

The chart of the confidence interval width as a function of number of measurements and plot size can be used as a support in sampling design to obtain a reliable  $K_s$  with the minimum number of samples.

The chart could be also used for estimating the minimum number of DRI measurements in other catchments that exhibit geo-morphological characteristics similar to those characterizing this study, i.e. an agricultural setting, slope angles less than  $10^\circ$  and silty soils. If spatial correlations of  $K_s$  are present, the proposed procedure represents an upper limit of the uncertainty to be expected. Finally, the methodology adopted here could be of interest to develop similar investigations in different areas.

A limitation of this work is that the  $K_s$  measurements through the catchment were not performed at the same time. Therefore a distortion of the spatial pattern of  $K_s$  cannot be ruled out because of possible changes of the local values. This is a problem that cannot be completely solved, at least considering the limits of the currently available devices, and that in any case should not have significantly affected the main features of the  $K_s$  spatial variability field obtained in this study.

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